UAV LiDAR Sensor for Wide Area Coverage with Extra Large Field of View

NEW

RIEGL VUX®-100[25]

- *laser pulse repetition rate up to 1,500 kHz*
- *measurement rate up to 1,333,333 meas./sec*
- *scan speed up to 200 lines/second*
- *operating flight altitude up to 360 m / 1,200 ft @ 60% target reflectivity*
- *Field of View up to 160°*
- *compact & lightweight (2.36 kg / 4.4 lbs)*
- *cutting edge RIEGL technology providing:*
  - *echo signal digitization*
  - *multiple target capability*
  - *online waveform processing*
  - *multiple-time-around processing*
- *easily mountable to unmanned platforms (UAVs) and small manned aircraft*
- *mechanical and electrical interface for IMU/GNSS integration*
- *interfaces for up to 2 external cameras*
- *scan data storage on internal SSD Memory*
- *removeable CFAST® memory card*

The *RIEGL* VUX-100[25] is a lightweight and versatile airborne laser scanner offering a wide field of view of 160 degrees and an extremely high pulse repetition rate of up to 1,500 kHz.
The key features – especially the extra large field of view – provide an extra wide area coverage, which is especially of advantage for applications like mapping of complex terrain and narrow canyons.

The scanner provides an internal data storage capacity of 2 TByte and a removeable CFast card and is equipped with interfaces for integration of an external IMU/GNSS system. Additionally, interfaces for up to two optional external cameras are available.

The sophisticated design of the *RIEGL* VUX-100[25] allows smooth integration on UAS/UAV/RPAS, small manned aeroplanes (like gyrocopters), but also on helicopters. It is offered both, as stand-alone UAV LiDAR sensor and also in various fully-integrated UAV-based laser scanning system configurations with appropriate IMU/GNSS system and optional cameras. This allows the scanner to perfectly meet all the specific requirements of the customers' applications.

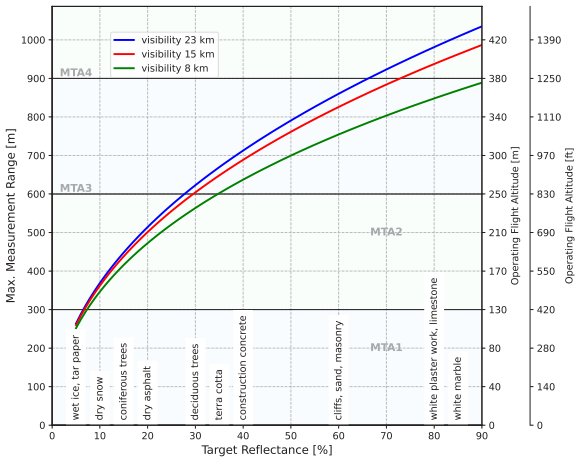
Typical applications include

- *Corridor Mapping: Power Line, Railway Track and Pipeline Inspection*
- *Topography in Open-Cast Mining*
- *Surveying of Urban Environments*
- *Archeology and Cultural Heritage Documentation*
- *Agriculture & Forestry*

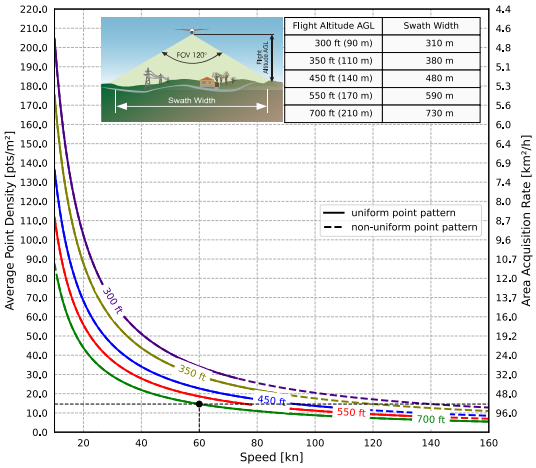
visit our website
www.riegl.com

RIEGL®
LASER MEASUREMENT SYSTEMS

PRR = 500 kHz

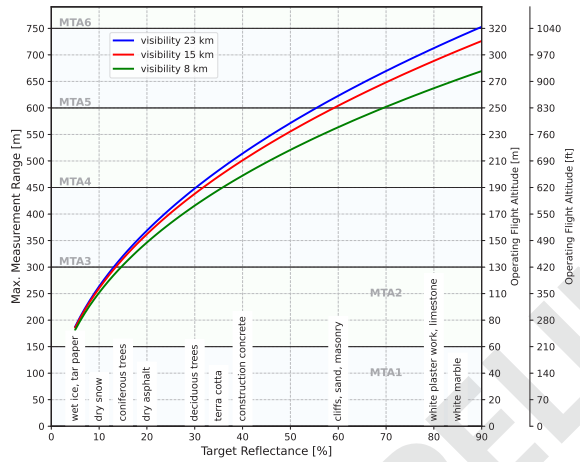


Operating Flight Altitude AGL given for the following conditions:
FOV 100°, ambiguity resolved by multiple-time-around (MTA) processing, average ambient brightness, target size ≥ laser footprint, roll angle ±5



Example: VUX-100[25] at 500,000 pulses/sec, laser power level 100%
Altitude = 700 ft AGL, Speed 60 kn, resulting point density ~ 14.6 pts/m²

PRR = 1000 kHz



Operating Flight Altitude AGL given for the following conditions:
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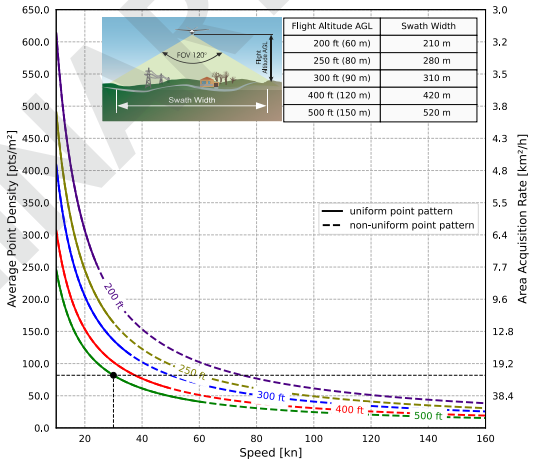
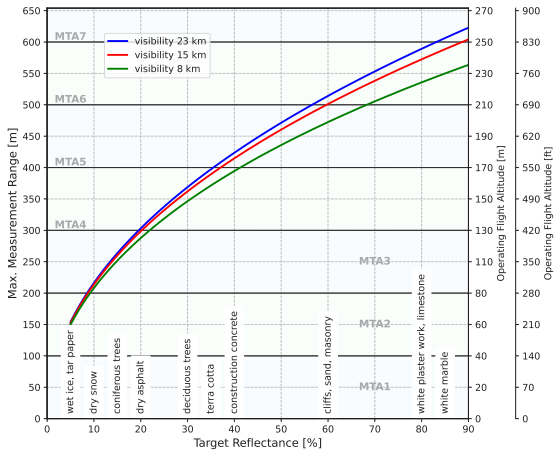
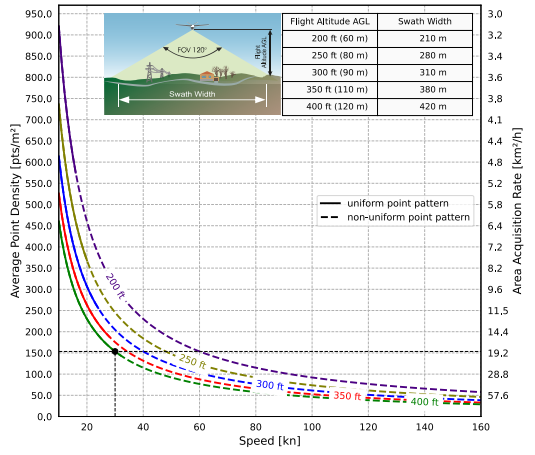


Example: VUX-100[25] at 1,000,000 pulses/sec, laser power level 100%
Altitude = 500 ft AGL, Speed 30 kn, resulting point density ~ 81.8 pts/m²

PRR = 1500 kHz

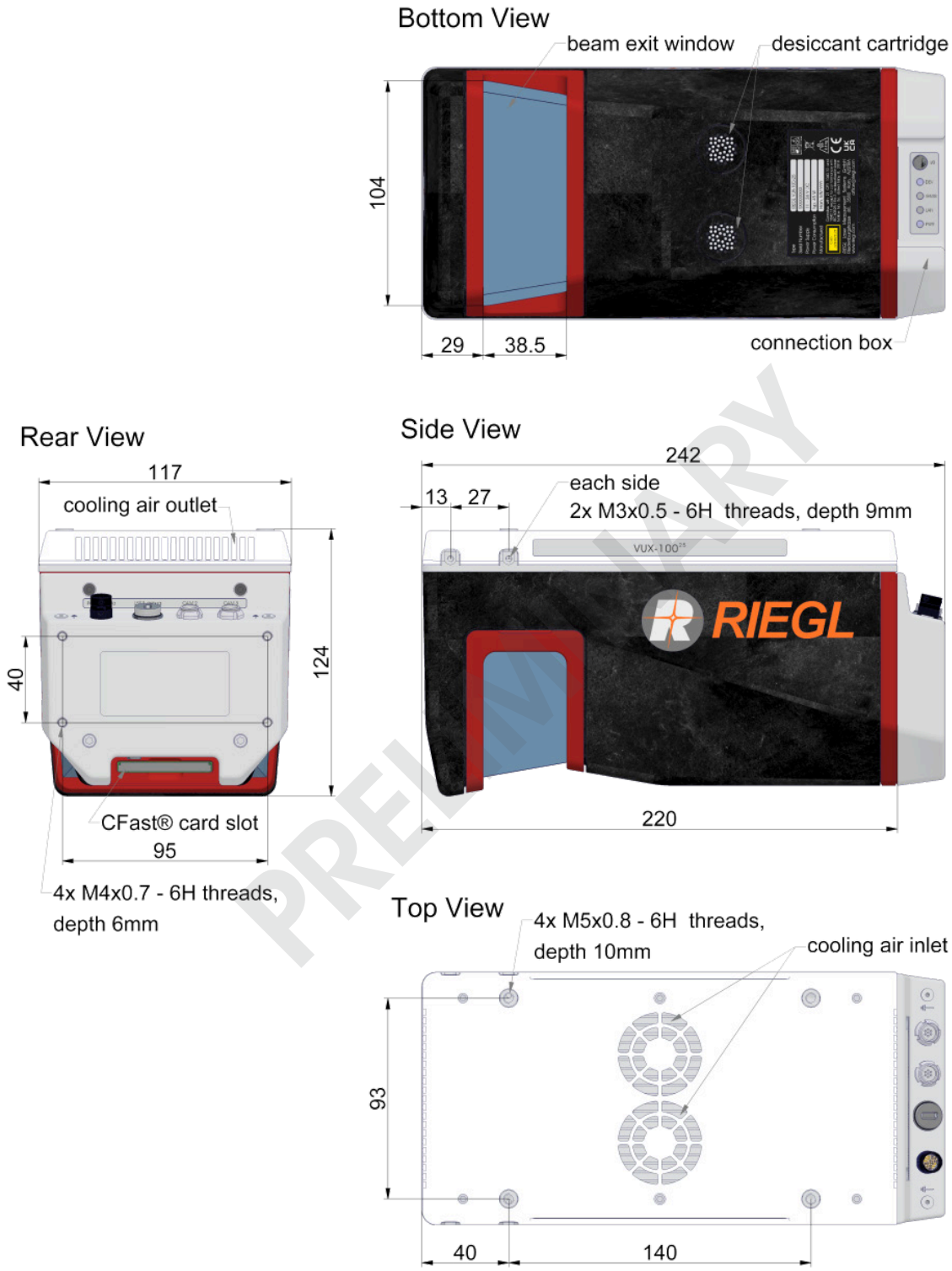


Operating Flight Altitude AGL given for the following conditions:
FOV 100°, ambiguity resolved by multiple-time-around (MTA) processing, average ambient brightness, target size ≥ laser footprint, roll angle ±5



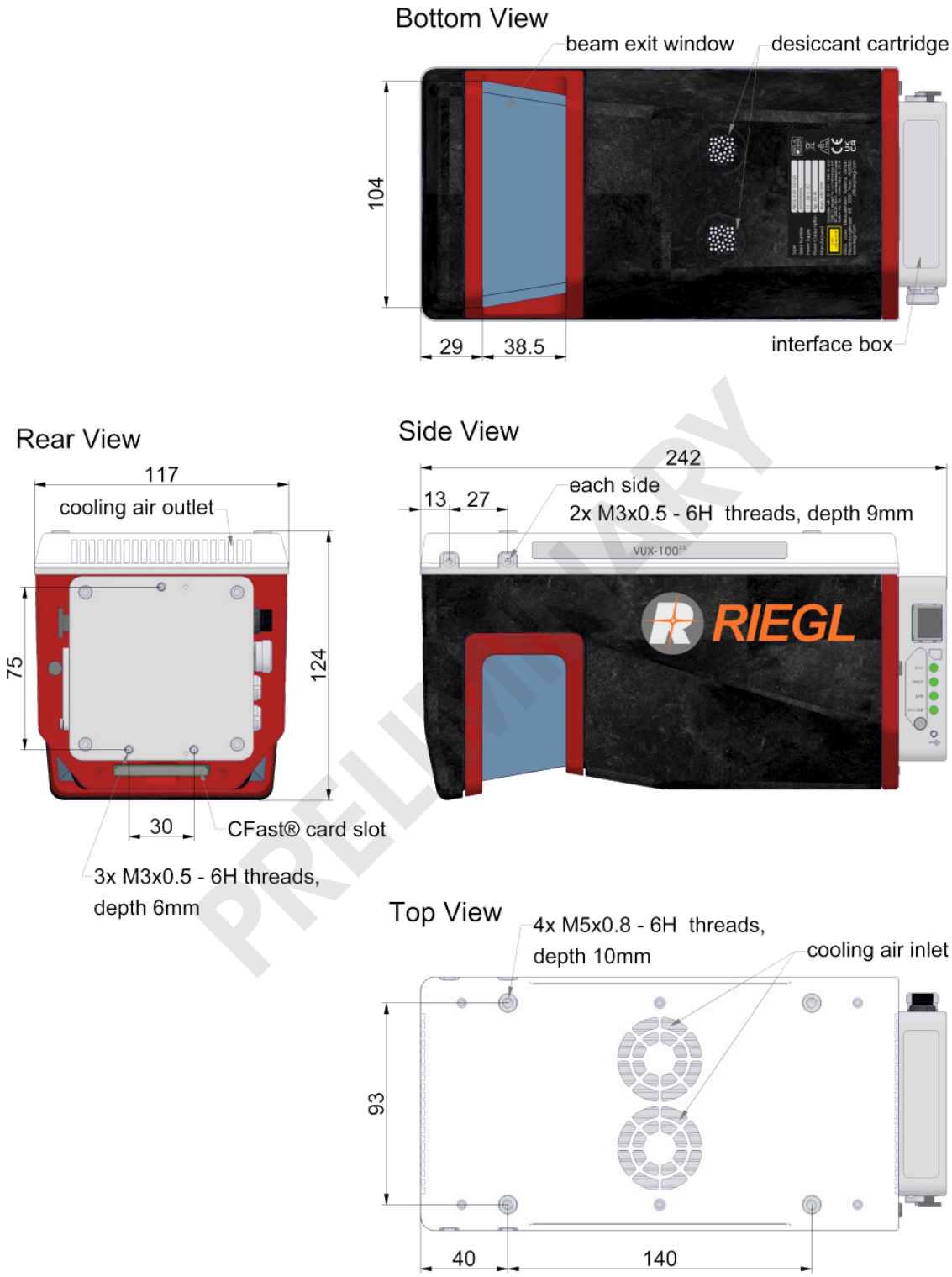
Example: VUX-100[25] at 1,500,000 pulses/sec, laser power level 100%
Altitude = 400 ft AGL, Speed 30 kn, resulting point density ~ 153.4 pts/m²

RIEGL VUX-100[25] UAV LiDAR Sensor with Connection Box



all dimensions in mm

RIEGL VUX-100[25] UAV LiDAR Sensor with Interface Box



all dimensions in mm

Laser Product Classification

Class 1 Laser Product according to IEC60825-1:2014
The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for conformance with IEC 60825-1 Ed.3., as described in Laser Notice No. 56, dated May 8, 2019.

Range Measurement Performance

Measuring Principle: time of flight measurement, echo signal digitization, multiple target capability, online waveform processing, multiple-time-around-processing

Laser Pulse Repetition Rate PRR [1]	*500 kHz*	*1000 kHz*	*1500 kHz*
Max. Measuring Range [2] [3] [4]			
natural targets ρ ≥ 20 %	510 m	370 m	300 m
natural targets ρ ≥ 60 %	860 m	620 m	510 m
natural targets ρ ≥ 80 %	980 m	710 m	590 m
Max. Operating Flight Altitude AGL [2] [5]			
@ ρ ≥ 20 %	220 m (700 ft)	160 m (500 ft)	130 m (400 ft)
@ ρ ≥ 60 %	360 m (1200 ft)	260 m (850 ft)	220 m (700 ft)
Max. Number of Targets per Pulse [6]	30	14	9

1) Rounded average PRR.
2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.
3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. Range ambiguities have to be resolved by multiple-time-around processing.
4) Within FOV ± 65° = 130° full measuring range performance, over 130° to 160° 90% of full measuring range performance.
5) Considering max. effective FOV 120°, additional roll angle ± 5°.
6) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus the achievable range is reduced.

Minimum Range	5 m
Accuracy [7] [9]	10 mm
Precision [8] [9]	5 mm
Laser Pulse Repetition Rate [1] [10]	up to 1500 kHz
Max. Effective Measurement Rate [1]	up to 1,333,333 meas./sec. (@ 1500 kHz PRR & 160° scan angle)
Echo Signal Intensity	for each echo signal, high-resolution 16 bit intensity information is provided
Laser Wavelength	near infrared
Laser Beam Divergence	0.4 mrad [11]
Laser Beam Footprint (Gaussian Beam Definition)	40 mm @ 100 m, 200 mm @ 500 m, 400 mm @ 1000 m

7) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
8) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.
9) One sigma @ 150 m range under *RIEGL* test conditions.
10) User selectable.
11) Measured at the $1/e^2$ points. 0.4 mrad corresponds to an increase of 40 mm of beam diameter per 100 m distance.

Scanner Performance

Scanning Mechanism	rotating polygon mirror
Scan Pattern	parallel scan lines
Field of View (selectable)	± 80° = 160°
Scan Speed (selectable)	50 - 200 lines/sec
Angular Step Width Δ ϑ (selectable) between consecutive laser shots	0.006° ≤ Δ ϑ ≤ 0.24° [12] [13]
Angle Measurement Resolution	0.001°
Scan Sync (optional)	scanner rotation synchronization

Data Interfaces

Configuration, Scan Data Output & Communication with External Devices	2x LAN 10/100/1000 MBit/sec [14] [15]
GNSS Interface	Serial RS-232 interface, TTL input for 1pps synchronisation pulse, accepts different data formats for GNSS-time information
General IO & Control [14]	1 x TTL input, 1x TTL output, 1 x Remote on/off
Camera Interfaces at connector panel	2x power (max. 1.2 A), trigger, exposure, and GNSS RS-232 Tx & PPS
Camera Interfaces via multi purpose connector [16]	1x trigger and exposure
IMU Interface (optional)	IMU data, power

General Technical Data

Power Supply Input Voltage / Consumption	11 - 34 V DC / typ. 45 W
Main Dimensions (L x W x H)	242 mm x 117 mm x 124 mm (with interface box) 225 mm x 117 mm x 124 mm (without interface box)
Weight	approx. 2.36 kg (with interface box)
Humidity	max. 80 % non condensing @ 31°C
Protection Class	IP64, dust and splash-proof
Max. Flight Altitude (operating & not operating)	18 500 ft (5 600 m) above MSL (Mean Sea Level)
Temperature Range	-10°C up to +40°C (operation) / -20°C up to +50°C (storage)

12) The angular step width depends on the selected laser PRR.
13) The maximum angular step width is limited by the maximum scan rate.
14) 1x externally available via multi-purpose connector
15) 1x available directly on optional interface box
16) externally available via connection board (including 1x power camera)

Data Storage

Internal Data Storage	Solid State Disc SSD, 2 TByte
Memory Card Slot	for CFAST® [1] industrial memory card 480 GB (can be upgraded to 1TByte)

External IMU & GNSS (optional)

	RIEGL RiLOC-F	Applanix APX-20 UAV [3]	Applanix AP+50 [3] [4]
IMU Accuracy [2]			
Roll, Pitch	-	0.015°	0.005°
Heading	-	0.035°	0.010°
IMU Sampling Rate	up to 700 Hz	200 Hz	200 Hz
Position Accuracy (typ.)	0.02 - 0.03 m	0.02 - 0.05 m	0.02 - 0.05 m
System Total Weight (approx.)	2.7 kg	3.0 kg	3.6 kg [5]

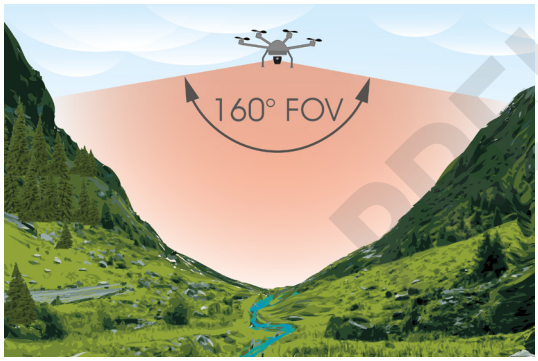
1) CFast is a registered trademark of CompactFlash Association.
2) Accuracy specifications for post-processed data
3) See technical details at the according Applanix datasheet
4) Use of the RiSYS-CU-23 Control Unit is mandatory
5) Total weight includes RiSYS-CU-23 Control Unit (0.9 kg)

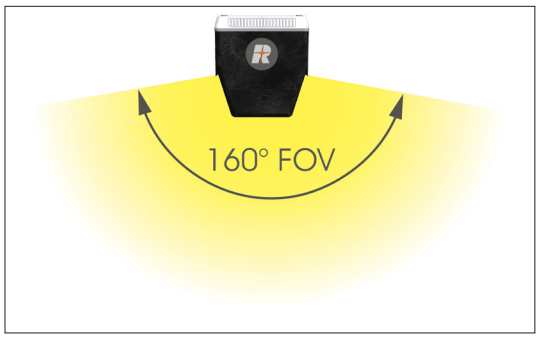
all dimensions in mm

RIEGL VUX-100[25] equipped with RIEGL RiLOC-F

RIEGL VUX-100[25] equipped with APX-20 UAV

RIEGL VUX®-100[25] Field of View & System Integration





160° extra large FOV for wide area coverage

RIEGL VUX-100[25] LiDAR sensor with APX-20 UAV IMU/GNSS unit fully integrated on Acecore Zoe multirotor UAV platform

RIEGL® LASER MEASUREMENT SYSTEMS

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RIEGL USA Inc., *Headquarters North America*

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